## DCP552 Digital Control Programmer

The DCP552 is a high-function programmer/ controller supporting two channels (up to 49 program patterns per channel) to which thermocouple, resistance temperature detector (RTD), DC voltage, DC current and other signals can be input.
The DCP552 supports a memory card interface, 16 event outputs, 16 external switch inputs and a wide range of other functions as part of the standard specification.

## FEATURES

- Accuracy of $\pm 0.1 \%$ FS. Easy-to-view large display characters. Compact design
- Any input type can be selected by console key operation.
- Easy operation aided by guidance messages
- Up to 49 program patterns can be stored to each channel and up to 99 segments can be programmed to each pattern.
- Program patterns can be saved or loaded using the Smart Proximity Card (sold separately).
- The Smart Proximity Card uses highly durable and non-contact type cards

- Any event can be selected to each channel and set for the 16 event outputs, and code events comprising a combination of two or more points can be set.
-16 external switch inputs allow the control of remote selection of program Nos. or operation on each channel separately or both channels simultaneously
-CE marking-compatible
Applicable standards: EN61O 10-1, EN5008 1-2, EN50082-2

BASIC FUNCTION BLOCKS of DCP552


| $\begin{aligned} & E \\ & \text { E } \\ & 0 \\ & 0 \\ & 0 \end{aligned}$ | Number of programs | 49 programs x 2 channels |
| :---: | :---: | :---: |
|  | Number of segments | 99 per program, total 2000 |
|  | Segment setting system | RAMP-X: Set by set points (SP) and time. <br> RAMP-T: Set by set points (SP) and ramp (13) <br> RAMP-E: Set by set points (SP) and ASP per external switch input 1 pulse |
|  | Segment time | 0 to 500 hours 0 minute, 0 to 500 minutes 0 second, 0.0 to 3000.0 seconds (time unit selectable) |
|  | Segment ramp | 1 to 10000 U/hour, 1 to 10000 U/minute, 1 to 10000 U/second (time unit selectable) |
|  | Segment ASP | 1 to $10000 \mathrm{U} / \mathrm{l}$ pulse |
|  | Number of aubfunctions | 4000 |
|  | Sub-function action | Events, PID set, output limiter set, G. Soak, PV shift, repeat |
|  | Eventa (16) | Set operating point corresponding to event type |
|  | PID set No. | Set 0 (continuation of previous segment), 1 to 9 , A set (automatically switched) and ON-OFF control |
|  | Output limiter aet | Set 0 (continuation of previous segment), 1 to 9 |
|  | G.Seek | Set type (start/end points and overall) and G.Soak width 0 to 1000 U . |
|  | PV shift | -10000 to +10000 U |
|  | Repeat | Set return destination segment No. and repeat count. |
|  | PV start | Set type (rising/falling or both) for each program. |
|  | Cycle | Set cycle count for each program. |
|  | Pattern link | Set program No. 0 to 49 (0: no link) for each program. |
|  | Tag | Set 8 alphanumerics or symbols for each program. |
|  | Basic time accuracy | $\pm 0.01 \%$ (segment time setting $=0$, with 0.1 second delay for each repeat and cycle) |
|  | Input type | Thermocouple, resistance temperature detector (RTD), DC voltage, DC current multi-range (See pages 6, 7.) |
|  | Sampling cycle | 0.1 seconds |
|  | Input bias current | Thermocouple, DC voltage input: Max. $\pm 1.3 \mathrm{uA}$ (at peak value and reference conditions) 1 V or higher range: Max. $-3 \mu \mathrm{~A}$ |
|  | Input impedance | DC current input: approx. $50 \Omega$ (under operating conditions) |
|  | Measuring current | RTD input: Approx. 1 mA current flow from terminal A (under operating conditions) |
|  | Influence of wiring resistance | Thermocouple, DC voltage input: Thermocouple: $0.5 \mu \mathrm{~V} / \Omega$ <br>  DC voltage (max. 1 V range): $0.5 \mu \mathrm{~V} / \Omega$  <br>  DC voltage ( 5 V range): $3 \mu \mathrm{~V} / \Omega$ <br>  DC voltage (10 V range): $6 \mu \mathrm{~V} / \Omega$  <br> RTD input: Max. $\pm 0.01 \% \mathrm{FS} / \Omega$ in wiring resistance range 0 to $10 \Omega$  <br>  Range of F01, F33, P01 and $\mathrm{P} 33: \pm 0.02 \% \mathrm{FS} / \Omega$ max.  |
|  | RTD input allowable wiring resistance | -Ranges other than F01, F33, P01 and P33: 85 , max. <br> (including Zener barrier resistance. Note that site adjustment is required.) <br> . Ranges of F01, F33, PO1 and P33: $10 \Omega$ max. <br> (Zener barrier cannot be used.) |
|  | Allowable parallel resistance | Thermocouple disconnection detection allowable parallel resistance: $1 \mathrm{M} \Omega \mathrm{min}$. |
|  | Max. allowable Input | Thermocouple, DC voltage input: -5 to +15 V dc DC current input: $\quad 50 \mathrm{~mA} \mathrm{dc}, 2.5 \mathrm{~V}$ dc |
|  | Burnout | Detection selectable |
|  | Over-range detection threshold | 110\%FS min.: Upscaled <br> $-10 \%$ FS max.: Downscaled (Note that F50 range is not downscaled.) |
|  | Cold-junction compensation accuracy | $\pm 0.5^{\circ} \mathrm{C}$ (under standard conditions) |
|  | Cold- junction compensation system | Internal/external ( $0^{\circ} \mathrm{C}$ only) compensation selectable |
|  | Scaling | -19999 to +20000 U (possible in case of linear input only. Inverse scaling possible. Decimal point position settable at any point) |
|  | Square root extraction | Possible. Dropout: 0.2 to $10.0 \%$ in case of DC current or DC voltage range |
|  | PV equalizer (linearization table approximation) | PV1: 9 segments (1 O points set) PV2: 9 segments (1 O points set) CP: 9 segments (1 0 points set) |
|  | Input bias | -1000 to +1000 U variable |
|  | Digital filter | 0.0 to 120.0 seconds variable (0.0: filter OFF) |


|  | Number of inputs | 16 |  |
| :---: | :---: | :---: | :---: |
|  | Types of connectable outputs | Dry contacts (relay contact) and open-collector (current sink to ground) |  |
|  | Terminal voltage (open) | $8.5 \mathrm{~V} \pm 0.5 \mathrm{~V}$ between common terminals (terminals 12,40 ) and each input terminal (under operating conditions) |  |
|  | Terminal current (short-circuit) | Approx. 6 mA between each terminal (under operating conditions) |  |
|  | Allowable contact resistance (dry contact) | ON: 250 ohm max. (under operating conditions) OFF: 100 kohm min. (under operating conditions) |  |
|  | Voltage drop (at open-collector ON) | 2 V max. (under operating conditions) |  |
|  | Leakage current (at open-collector OFF) | 0.1 mA max. (under operating conditions) |  |
|  | Assignments (fixed) | RUN, HOLD, RESET, ADV, program No., CH1 operation cancel, CH 2 operation cancel |  |
|  | Assignments (variable) | RAMP-E, FAST, AT, AUTO/MANUAL, G.Soak cancel, auto-load, $\mathrm{O}_{2}$ sensor check |  |
|  | Input sampling cycle | 0.1 seconds |  |
|  | ON detectlon min. hold time | 0.2 seconds (0.4 seconds for program No.) |  |
|  | Upper display | Green 5 -digit, 7 -segment LED <br> This displays PV values in the basic display state. Item codes are displayed in the parameter setup. |  |
|  | Lower display | Orange 5 -digit, 7 -segment LED <br> This displays SP and output \% in the basic display state. Setting values are displayed in the parameter setup. |  |
|  | Program No. display | Green 2-digit, 7 -segment LED <br> This displays program No. in the basic display state. |  |
|  | Segment No. display | Green 2-digit, 7-segment LED <br> This displays segment No. in the basic display state. <br> Item Nos. are displayed in parameter setup, and alarm No. is displayed when alarm occurs. |  |
|  | Message display | This displays output graph, deviation graph, event state and tags in the basic display state. This displays reference messages in the parameter setup and program setup. This displays operation details and operation results of memory card operation. |  |
|  | Profile display | 7 orange LEDs <br> Displays program pattern rise, soak and fall trends. |  |
|  | Status displays | 22 round LEDs  <br> Modes: RUN, HLD, MAN, PRG (green) <br> Display details: PV, SP, OUT, TM, CYC, SYN, DEV (green), EG1, EG2 (red) <br> Battery voltage: BAT (red) (blinks at low voltage) <br> Status: AT (green) |  |
|  | Operation keys | 18 rubber keys |  |
|  | Loader connector port | 1 (dedicated cable with stereo miniplugs) |  |
| $\begin{aligned} & \text { g } \\ & \text { 8 } \\ & \text { B } \end{aligned}$ | Progrsm operation modes | READY: Ready to run program (control stop/program No. selectable) <br> RUN: Program run <br> HOLD: Program hold <br> FAST: Program, fast-forward <br> END: Program end <br> READY FAST: Ready to run and fast-forward program |  |
|  |  | AUTO: Automatic operation <br> MANUAL: Manual operation (output can be controlled on console) |  |
|  | Constant-value operation modes | READY: Ready to run program (control stop) <br> RUN: |  |
|  |  | AUTO: Automatic operation <br> MANUAL Manual operation (output can be controlled on console) |  |
| $\begin{aligned} & \text { 힣 } \\ & \text { 휸 } \\ & 0 \end{aligned}$ | PID controls | Proportional band (P) | 0.0 to 1000.0\% (0.0: ON-OFF control) |
|  |  | Reset time (1) | 0 to 3600 seconds. 0 seconds: PD control |
|  |  | Rste time (D) | 0 to 1200 seconds. 0 seconds: PI control |
|  |  | MV limit | Lower limit: -5.0 to upper limit \% <br> Upper limit: Lower limit to $\mathbf{+ 1 0 5 . 0 \%}$ |
|  |  | Manual reset | 0.0 to 100.0\% |


|  | PID controls | Nu mber of PID sets | 16 sets for program operation (9 segment unique sets + 7 sets for automatic zone selection) |
| :---: | :---: | :---: | :---: |
|  |  | PID set selection | Segment designation/automatic zone seiection can be switched by program operation. |
|  |  | MV change | 0.1 to 110.0\%/0.1 seconds |
|  |  | Auto-tuning | Automatic setting of PiD value by limit cycle system |
|  |  | ON-OFF control differential | 0 to 1000 U |
|  | Direct/reverse action switching | Possible |  |
| $\begin{aligned} & \text { on } \\ & \frac{1}{3} \\ & \frac{0}{3} \\ & 0 \end{aligned}$ | Auxiliary output | Output types | SP1, PV1, deviation 1, MV1, SP2, PV2, deviation 2, $\mathrm{O}_{2}$ sensor mV value |
|  |  | Scaling | Possible |
|  | Current output (SG) CH1, CH2 auxiliary outputs CH1, CH2 | Output current: <br> Allowable load resistan <br> Output accuracy: <br> Output resolution: <br> Max. output current: <br> Min. output current: <br> Output updating cycle: <br> Open terminai voitage: | 4 to 20 mA dc <br> 600 ohm max. (under operating conditions) $\pm 0.1 \%$ FS max. (under standard conditions) $1 / 10000$ <br> 21.6 mA dc <br> 2.4 mA dc <br> 0.1 seconds <br> 25 V max. |
|  | Voltage output (6D) CH1, CH2 | Allowable load resistan Load current adjustme Variable open terminal OFF leakage current: Output response time: <br> Output resolution: Time-proportional cycle: | ce: $600 \Omega$ max. (under operating conditions) <br> t: 2 to 22 mA variable <br> voltage: 25 V max. <br>  100 PA max. <br>  At ON-OFF $600 \Omega$ load: 0.5 ms max. <br>  At OFF-ON $600 \Omega$ load: 0.5 ms max. <br>  $1 / 1000$ <br>  1 to 240 seconds variabie |
|  | Open-collector output (8D) CH1 CH2 | External supply voltage Max. load current OFF leakage current: ON residual voltage: Output resolution: <br> Time-proportional cycl | ```12 to 24 Vdc \(100 \mathrm{~mA} / \mathrm{load}\) 0.1 mA max. 2 V max. 1/1000 1 to 240 seconds variable``` |
| Event outputs | Open-collector | External supply voltage Max. Ioad current: Max. common current: OFF leakage current: ON residual voltage | 12 to 24 V dc 70 mAload 500 mA 0.1 mA max. 2 V max. |
|  | Event types | PV type | PV, deviation, w/deviation standby, absoiute value deviation, w/ absoiul deviation standby, PV rate-of-change, SP, MV, G.Soak absolute valued w/G.Soak absolute value deviation standby, PV1 constant operation, PV2 constant operation |
|  |  | Time type | Time events, RAMP-E time monitor, segment time, program time |
|  |  | Code type | Code event, code event w/ timer, program No. binary code, segment No. binary code, program No. BCD code, segment No. BCD code |
|  |  | Mode type | Unique segment, RUN+HOLD+END+FAST, HOLD, READY+READY FAST, END G.Soak standby, MANUAL, AT executing, FAST+ READY FAST, console operation in progress, RUN, advance, all alarms, PV range alarm, controller alarm, $\mathrm{O}_{2}$ sensor error, low battery voltage |
|  | Event hysteresis | In case of PV type set, | 0 to 1000 U |
|  | Event ON delay | 0.0 to 3000.0 can be s | to four events |
| Q00000$E$$E$$E$00 | RS-485 | Network | Multidrop <br> This controller is provided with only slave instrument functionality excep connected to ST221 (dedicated display device). <br> 1 to 16 units max. (DIM) <br> 1 to 31 units max. (CMA, SCM) |
|  |  | Data flow | Half dupiex |
|  |  | Synchronization | Start-stop synchronization |
|  |  | Transmission system | Balanced (differential) |
|  |  | Data iine | Bit seriai |
|  |  | Signal line | 5 transmit/receive lines (3-wire connection also possible) |
|  |  | Transmission speed | 1200, 2400,4800, 9600 bps |
|  |  | Transmission distance | 500 m max. (totai) <br> ( 300 m max. for MA500 DIM connection) |
|  |  | Other | Conforming to RS-485 interface specifications |



|  | Operating conditions | Amblent temperature range |  | 0 to $50^{\circ} \mathrm{C}$ (ambient temperature at the bottom side of case when gang-mounted) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Ambient humidity range |  | 10 to 90\%RH (condensation not allowed) |  |  |  |
|  |  | Rated power voltage |  | 100 to 240 V ac |  |  |  |
|  |  | Allowable power voltage |  | 90 to 264 V ac |  |  |  |
|  |  | Power frequency |  | $50 \pm 2 \mathrm{~Hz}$, or $60 \pm 2 \mathrm{~Hz}$ |  |  |  |
|  |  | Vibration resistance |  | 0 to $1.96 \mathrm{~m} / \mathrm{s}^{2}$ |  |  |  |
|  |  | Shock resistance |  | 0 to $9.80 \mathrm{~m} / \mathrm{s}^{2}$ |  |  |  |
|  |  | Mounting angle |  | Reference plane (vertical) $\pm 10$ degrees |  |  |  |
|  | Transport/storage conditions | Ambient temperature range |  | -20 to $+70^{\circ} \mathrm{C}$ |  |  |  |
|  |  | Ambient humidity range |  | 10 to $95 \%$ RH (condensation not allowed) |  |  |  |
|  |  | Vibration resistance |  | 0 to $4.90 \mathrm{~m} / \mathrm{s}^{2}$ ( 10 to 60 Hz for 2 hours each in $X, Y$ and $Z$ directions) |  |  |  |
|  |  | Shock resistance |  | 0 to $490 \mathrm{~m} / \mathrm{s}^{2}$ (3 times vertically) |  |  |  |
|  |  | Package drop test |  | Drop height: 60 cm (1 angle, 3 edges and 6 planes; free fall) |  |  |  |
|  | Terminal ecrew | M3.5 self-tapping screws |  |  |  |  |  |
|  | Terminal screw tightening torque | 0.76 to $0.98 \mathrm{~N} \cdot \mathrm{~m}$ |  |  |  |  |  |
|  | Mask/case materials | Mask Multilon |  |  | Case: Multilon |  |  |
|  | Mask/case color | Mask: Dark gray (Munsell5Y3.5/1) |  |  | Case: Light gray (Munsell2.5Y7.5/1) |  |  |
|  | Installation | Specially desioned mountina bracket |  |  |  |  |  |
|  | Weight | Approx. 1.5 kg |  |  |  |  |  |
|  | Item | Model No. | Q'tv |  | Item | Model No. | Q'ty |
|  | Unit Indicating label | - | 1 |  | Soft dust-proof cover | 61446141-001 | - |
|  | Mounting bracket | 81446044-001 | 1 set (2 p'c |  |  |  |  |
|  | User's Manual | CP-UM-5017E | 1 |  | Lithium battery set | 81448140-001 | Approx. 200 g |
|  |  |  |  |  | Memory csrd (RAM, battery replacement not possible) | SKMO08A <br> SKM016A <br> SKM064A | Approx. 30 g |

## Table 1 Input Types and Ranges (selectable in setup)

- Thermocouple

| Input Type |  |  | Input Range (FS) |  | Accuracy (under standard conditions) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Symbol | Code | Range No. | ${ }^{\circ} \mathrm{C}$ | "F |  |  |
| K (CA) | K46 | 16 | -200.0 to +200.0 | -300.0 to +400.0 | $\pm 0.1 \% \mathrm{FS}$ |  |
| K (CA) | K09 | 0 | 0.0 to 1200.0 | 0 to 2400 | $\pm 0.1 \%$ FS |  |
| K (CA) | K08 | 1 | 0.0 to 800.0 | 0 to 1600 | $\pm 0.1 \% \mathrm{FS}$ |  |
| K (CA) | K04 | 2 | 0.0 to 400.0 | 0 to 750 | $\pm 0.1 \% \mathrm{FS}$ |  |
| E (CRC) ${ }^{-}$ | E08 | 3 | 0.0 to 800.0 | 0 to 1800 | $\pm 0.1 \%$ FS |  |
| J (IC) | J08 | 4 | 0.0 to 800.0 | 0.0 to 1600 | $\pm 0.1 \% \mathrm{FS}$ |  |
| T (CC) | T44 | 5 | -200.0 to +300.0 | -300 to +700 | $\pm 0.1 \%$ FS | $\pm 0.3 \%$ FS between $-200^{\circ} \mathrm{C}$ to $-45^{\circ} \mathrm{C}$ |
| B (PR30-6) | B18 | 6 | 0.0 to 1800.0 | 0 to 3300 | $\pm 0.1 \% \mathrm{FS}$ | $\pm 4.0 \%$ FS between 0 to $260^{\circ} \mathrm{C}, \pm 0.15 \%$ FS between 260 to $800^{\circ} \mathrm{C}$ |
| R (PR13) | R16 | 7 | 0.0 to 1600.0 | 0 to 3100 | $\pm 0.1 \% \mathrm{FS}$ |  |
| S (PR1 0) | S16 | 8 | 0.0 to 1600.0 | 0 to 3100 | $\pm 0.1 \%$ FS |  |
| W (WRe5-26) | W23 | 9 | 0.0 to 2300.0 | 0 to 4200 | $\pm 0.1 \% \mathrm{FS}$ |  |
| W (WRe5-26) | W14 | 10 | 0.0 to 1400.0 | 0 to 2552 | $\pm 0.1 \% \mathrm{FS}$ |  |
| PR40-20 | D19 | 11 | 0.0 to 1900.0 | 0 to 3400 | $\pm 0.2 \%$ FS | $\pm 0.9 \%$ FS between 0 to $300^{\circ} \mathrm{C}, \pm 0.5 \%$ FS between 300 to $800^{\circ} \mathrm{C}$ |
| N | U13 | 12 | 0.0 to 1300.0 | 32 to 2372 | $\pm 0.1 \%$ FS |  |
| PLII | Y13 | 13 | 0.0 to 1300.0 | 32 to 2372 | $\pm 0.1 \%$ FS |  |
| Ni-Ni.Mo | Z13 | 14 | 0.0 to 1300.0 | 32 to 2372 | $\pm 0.1 \% \mathrm{FS}$ |  |
| Golden iron chromel | 206 | 15 | 0.0 to 300.0 | K (K: Kelvin) | $\pm 0.4 \% \mathrm{FS}$ |  |

- Resistance temperature detector (RTD)

| Input Type |  |  | Input Range (FS) |  | Accuracy (under standard conditions) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Symbol | Code | Range No. | ${ }^{\circ} \mathrm{C}$ | 'F |  |  |
| JIS'89Pt100 (IEC Pt100 ת) | F50 | 64 | -200.0 to +500.0 | -300.0 to +900.0 | $\pm 0.1 \% \mathrm{FS}$ |  |
|  | F46 | 65 | -200.0 to +200.0 | -300.0 to +400.0 | $\pm 0.1 \% \mathrm{FS}$ |  |
|  | F32 | 66 | -100.0 to +150.0 | -150.0 to +300.0 | $\pm 0.1 \% \mathrm{FS}$ |  |
|  | F36 | 67 | -50.0 to +200.0 | -50.0 to +400.0 | $\pm 0.1 \%$ FS |  |
|  | F33 | 68 | -40.0 to +60.0 | -40.0 to +140.0 | $\pm 0.15 \%$ FS |  |
|  | F01 | 69 | 0,0 to 100.0 | 0.0 to 200.0 | $\pm 0.15 \%$ FS |  |
|  | F03 | 70 | 0.0 to 300.0 | 0.0 to 500.0 | $\pm 0.1 \% \mathrm{FS}$ |  |
|  | F05 | 71 | 0,0 to 500.0 | 0.0 to 900.0 | $\pm 0.1 \%$ FS |  |
| JIS'89JPt100 | P50 | 96 | -200.0 to +500.0 | -300.0 to +900.0 | $\pm 0.1 \% \mathrm{FS}$ |  |
|  | P46 | 97 | -200.0 to +200.0 | -300.0 to +400.0 | $\pm 0.1 \% \mathrm{FS}$ |  |
|  | P32 | 98 | -100.0 to +150.0 | $-150,0$ to +300.0 | $\pm 0.1 \% \mathrm{FS}$ |  |
|  | P36 | 99 | -50.0 to +200.0 | -50.0 to +400.0 | $\pm 0.1 \%$ FS |  |
|  | P33 | 100 | -40.0 to +60.0 | -40.0 to +140.0 | $\pm 0.15 \%$ FS |  |
|  | Pol | 101 | 0.0 to 100.0 | 0.0 to 200.0 | $\pm 0.15 \%$ FS |  |
|  | P03 | 102 | 0.0 to $\mathbf{3 0 0 . 0}$ | 0.0 to 500,0 | $\pm 0.1 \% \mathrm{FS}$ |  |
|  | P05 | 103 | 0,0 to 500.0 | 0.0 to 900,0 | $\pm 0.1 \%$ FS |  |

## - DC current, DC voltage

| Input Type |  |  | Input Range (FS) |  | Accuracy (under standard conditions) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Svmbol | Code | Ranae No. |  |  |  |  |
| mA (linear) | C01 | 48 | 4 to 20 mA | Programmable range <br> -19999 to +20000 <br> (decimal point position can be <br> changed) | $\pm 0.1 \%$ FS |  |
|  | Z51 | 52 | 2.4 to 20 mA |  | $\pm 0.1 \%$ FS |  |
| mV (linear) | M01 | 49 | 0 to 10 mV |  | $\pm 0.1 \%$ FS |  |
|  | L02 | 50 | -10 to +10 mV |  | $\pm 0.1 \%$ FS |  |
|  | - | 51 | 0 to 100 mV |  | $\pm 0.15 \% \mathrm{FS}$ |  |
| mA (linear) | C01 | 128 | 4 to 20 mA | Programmable range -19999 to +20000 <br> (decimal point position can be changed) | $\pm 0.15 \%$ FS |  |
|  | Z51 | 134 | 2.4 to 20 mA |  | $\pm 0.1 \%$ FS |  |
| V (linear) | - | 129 | 0 to 1 V |  | $\pm 0.1 \%$ FS |  |
|  | - | 130 | -1 to +1 V |  | $\pm 0.1 \%$ FS |  |
|  | Vol | 131 | 1 to 5 V |  | $\pm 0.1 \%$ FS |  |
|  | - | 132 | 0 to 5V |  | $\pm 0.1 \%$ FS |  |
|  | - | 133 | 0 to 10 V |  | $\pm 0.1 \%$ FS |  |
| $\mathrm{O}_{2}$ sensor* | - | 135 | 0 to 1250 mV <br> Carbon potential (CP value) indication range: $0.000 \text { to } 4.000 \% \mathrm{C}$ <br> (Note that PID control is calculated in input range 0.000 to $2.000 \%$ C.) <br> $\mathrm{O}_{2}$ partial pressure $\left(\mathrm{PO}_{2}\right)$ indication range: 0.000 to $1.500 \times 10-20 \mathrm{~atm}$ |  | $\pm 0.1 \%$ FS | When converted to mV value |

*     - Any $\mathrm{O}_{2}$ sensor made by Marathon Monitors, Cambridge, Corning, AACC (Advanced Atmosphere Control Corporation), and Furnace Control can be used.
- PV2 is fixed for the $\mathrm{O}_{2}$ sensor in the case of models supporting carbon potential,


## ! Handling Precautions

- The unit of code Z06 is Kelvin (K).
- The PV lower limit alarm does not occur with codes F50 and P50.
- The number of digits past the decimal point for DC current and DC voltage is programmable within the range 0 to 4.
- The PV upper limit alarm is output by the $\mathrm{O}_{2}$ sensor when the voltage exceeds 1375 mV . The PV lower limit alarm, however, is not output.


## MODEL SELECTION GUIDE

Key \#- I- II - III - IV - V

|  | I | II | III | IV | V |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Key No. | - | Number of PV inputs | Carbon Potential | Option | Additions | Specifications |
| DCP552 |  |  |  |  |  | Digital Programmable Controller (2-loop model) |
|  | E |  |  |  |  | Universal Output |
|  |  | 2 |  |  |  | Two Inputs |
|  |  |  | 0 |  |  | None |
|  |  |  | 1 |  |  | Oxygen Sensor Input for Carbon Potential |
|  |  |  |  | 0 |  | None |
|  |  |  |  | 1 |  | 1 Auxiliary output |
|  |  |  |  | 2 |  | 2 Auxiliary outputs, Communications |
|  |  |  |  |  | 00 | None |

EXTERNAL DIMENSIONS
(Unit: mm)


PANEL CUTOUT
(Unit: mm)



Input


Note: If voltage mode signals are input to PV input CH 1 (terminal Nos. (55), (56) and input CH 2 (terminal Nos. (36), (59) for current input by mistake, a large current might flow and cause the controller to malfunction. Before wiring to the current input terminals on the DCP552, make sure that current input signals are output correctly within the range 4 to 20 mA .

## Control output



## Auxiliary output



INTERNAL CIRCUIT OF EXTERNAL SWITCH INPUT


## COMMUNICATIONS I/O (OPTION)



## WIRING PRECAUTIONS

## 1. Isolating Inputs and Outputs Inside the Controller

Solid lines - show isolated items.
Dotted lines - - - - - show non-isolated items.

| PV input CH1 |  | Control output CH1 |
| :--- | :--- | :--- |
| PV input CH2 |  | Auxiliary output CH1 |
| Loader communications | Digital circuit | Control output CH2 |
| External switch input |  |  |
| Communications |  | Event output |
| Memory card input |  |  |

## 2. Noise Countermeasures for Instrument Power Supplies

(1) Reducing noise

Connect the DCP552 to a single-phase power supply for instruments, and take measures to prevent the influence of electrical noise.

(2) When there is a lot of noise

If there is a lot of electrical noise, we recommend inserting an insulating transformer in the power circuit and using a line filter.


## 3. Noise Generating Sources and Countermeasures

Generally, the following generate electrical noise:
Relays and contacts, electromagnetic coils, solenoid valves, power lines (in particular, 90 Vac min.) induction loads, inverters, motor

## WARRANTY / REMEDY

Honeywell warrants goods of its manufacture as being free of defective materials and faulty workmanship. Contact your local sales office for warranty information. If warranted goods are returned to Honeywell during the period of coverage, Honeywell will repair or replace without charge those items it finds defective. The foregoing is Buyer's sole remedy and is in lieu of all other warranties, expressed or implied, including those of merchantability
commutators, phase angle control SCR, radio communications equipment, welding equipment, high-voltage ignition equipment.

## (1) Fast-rising noise

CR filters are effective in countering fast-rising noise.
Recommended CR filter:
Yamatake Corporation Model No. 81446365-001

## (2) Noise with a high wave height

Varisters are effective in countering noise with a high wave height. However, note that the varister may become short-circuited when trouble occurs. Pay attention to this when providing a varister on a controller.
Recommended varister:
Yamatake Corporation Model No. 81446366-001 (for 100 Vac )
81446367-001 (for 200 Vac )

## 4. Ground

Use only the FG terminal 52 or 53 on the DCP552 for grounding. Do not ground across other terminals. When it is difficult to ground shielded cable, prepare a separate GND terminal plate (earth bar).
Ground type: $\quad 100 \Omega$ max.
Ground cable: $\quad 2 \mathrm{~mm}^{2} \mathrm{~min}$. annealed-copper wire (AWG14)
Cable length: Max. 20 m


## 5. Precautions During Wiring

(1) After providing anti-noise measures, do not bundle primary and secondary power leads together, or pass them through the same piping or wiring duct.
(2) Maintain a distance of at least 50 cm between I/O signal leads or communications leads and the power lead. Also, do not pass these leads through the same piping or wiring duct.

## 6. Inspection After Wiring

After wiring is completed, be sure to inspect and check the wiring state. Wrong wiring may cause controller malfunction or accidents.
and fitness for a particular purpose. Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this printing. However, we assume no responsibility for its use.
While we provide application assistance personally, through our literature and the Honeywell web site, it is up to the customer to determine the suitability of the product in the application.

## Sensing and Control

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