Honeywell

DCP552 Digital Control Programmer

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Specification

The DCP552 is a high-function programmer/ controller supporting two channels (up to 49 program patterns per channel) to which thermocouple, resistance temperature detector (RTD), DC voltage, DC current and other signals can be input.

The DCP552 supports a memory card interface, 16 event outputs, 16 external switch inputs and a wide range of other functions as part of the standard specification.

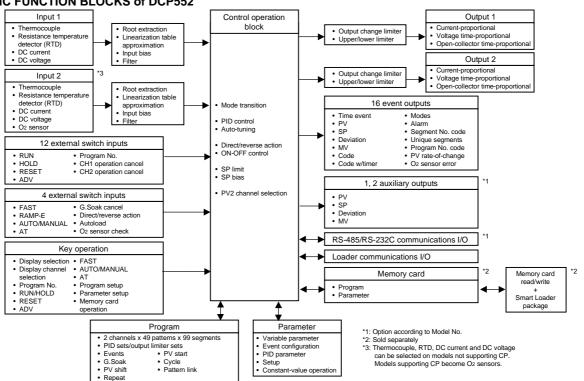
FEATURES

- •Accuracy of ±0.1%FS. Easy-to-view large display characters. Compact design
- Any input type can be selected by console key operation.
- Easy operation aided by guidance messages
- Up to 49 program patterns can be stored to each channel and up to 99 segments can be programmed to each pattern.
- Program patterns can be saved or loaded using the Smart Proximity Card (sold separately).
- The Smart Proximity Card uses highly durable and non-contact type cards



- . Any event can be selected to each channel and set for the 16 event outputs, and code events comprising a combination of two or more points can be set.
- .16 external switch inputs allow the control of remote selection of program Nos. or operation on each channel separately or both channels simultaneously
- •CE marking-compatible

Applicable standards: EN610 10-1, EN5008 1-2, EN50082-2



BASIC FUNCTION BLOCKS of DCP552

	1							
	Number of pro- grams	49 programs x 2 channels						
	Number of seg- ments	99 per program, total 2000						
	Segment setting	RAMP-X: Set by set points (SP) and time.						
	system	RAMP-T: Set by set points (SP) and time. RAMP-T: Set by set points (SP) and ramp (13)						
	System	RAMP-E: Set by set points (SP) and ASP per external switch input 1 pulse						
	Commont time	0 to 500 hours 0 minute, 0 to 500 minutes 0 second, 0.0 to 3000.0 seconds (time unit selectable)						
	Segment time							
	Segment ramp	1 to 10000 U/hour, 1 to 10000 U/minute, 1 to 10000 U/second (time unit selectable)						
	Segment ASP	1 to 10000 U/I pulse						
F	Number of aub- functions	4000						
Program	Sub-function action	Events, PID set, output limiter set, G. Soak, PV shift, repeat						
ĕ	Eventa (16)	Set operating point corresponding to event type						
_ ₽_	PID set No.	Set 0 (continuation of previous segment), 1 to 9, A set (automatically switched) and ON-OFF control						
	Output limiter aet	Set 0 (continuation of previous segment), 1 to 9						
	G.Seek	Set type (start/end points and overall) and G.Soak width 0 to 1000 U.						
	PV shift	-10000 to +10000 U						
	Repeat	Set return destination segment No. and repeat count.						
	PV start	Set type (rising/falling or both) for each program.						
	Cycle	Set cycle count for each program.						
	Pattern link	Set program No.0 to 49 (0: no link) for each program.						
	Тад	Set 8 alphanumerics or symbols for each program.						
	Basic time accu-	$\pm 0.01\%$ (segment time setting = 0, with 0.1 second delay for each repeat and cycle)						
	racy							
	Input type	Thermocouple, resistance temperature detector (RTD), DC voltage, DC current multi-range (See pages 6, 7.)						
	Sampling cycle	0.1 seconds						
	Input bias current	Thermocouple, DC voltage input: Max. ±1.3 uA (at peak value and reference conditions)						
	•	1 V or higher range: Max3 μA						
	Input impedance	DC current input: approx. 50 Ω (under operating conditions)						
	Measuring current	RTD input: Approx. 1 mA current flow from terminal A (under operating conditions)						
	Influence of wiring	Thermocouple, DC voltage input: Thermocouple: 0.5μ V/ Ω						
	resistance	DC voltage (max. 1 V range): $0.5 \ \mu V/\Omega$						
		DC voltage (5 V range): $3 \mu V/\Omega$						
		DC voltage (10 V range): 6 μ V/ Ω						
		RTD input: Max. $\pm 0.01\%$ FS/ Ω in wiring resistance range 0 to 10 Ω						
		Range of F01, F33, P01 and P33: ±0.02 %FS/Ω max.						
	RTD input allow-	•Ranges other than F01, F33, P01 and P33: 85 Ω max.						
	able wiring resis-	(including Zener barrier resistance. Note that site adjustment is required.)						
	tance	. Ranges of F01, F33, P01 and P33: 10 Ω max.						
		(Zener barrier cannot be used.)						
	Allowable parallel resistance	Thermocouple disconnection detection allowable parallel resistance: 1 M Ω min.						
Inputs	Max. allowable	Thermocouple, DC voltage input: -5 to+15V dc						
빌	Input	DC current input: 50 mA dc, 2.5V dc						
	Burnout	Detection selectable						
	Over-range	110%FS min.: Upscaled						
	detection threshold	-10%FS max.: Downscaled (Note that F50 range is not downscaled.)						
	Cold-junction							
	compensation	±0.5°C (under standard conditions)						
	accuracy							
	Cold- junction	Internal/automal (0°C ank) companyation extention						
	compensation system	Internal/external (0°C only) compensation selectable						
	Scaling	10000 to 120000 II (necesible in cose of linear input only Inverse cooling peecible. Desimal point pecifica						
	Scaling	-19999 to +20000 U (possible in case of linear input only. Inverse scaling possible. Decimal point pos settable at any point)						
	Square root extraction	Possible. Dropout: 0.2 to 10.0% in case of DC current or DC voltage range						
	PV equalizer	PV1: 9 segments (1 O points set)						
	(linearization table	PV2: 9 segments (1 0 points set)						
	approximation)	CP: 9 segments (1 O points set)						
	Input bias	-1000 to +1000 U variable						
	Digital filter	0.0 to 120.0 seconds variable (0.0: filter OFF)						
	U 14							

ı —	Number of inputs	16						
	Types of connect-		and open-collector (current sink to ground)					
	Terminal voltage (open)	conditions)	on terminals (terminals 12, 40) and each input terminal (under operating					
	Terminal current (short-circuit)	Approx. 6 mA between each terminal (under operating conditions)						
puts	Allowable contact resistance (dry contact)	ON: 250 ohm max. (under operating conditions) OFF: 100 kohm min. (under operating conditions)						
tch in	Voltage drop (at open-collector ON)	2 V max. (under operating conditions)						
≲xter⇔al switch inputs	Leakage current (at open-collector OFF)	0.1 mA max. (under operation	ng conditions)					
≷xte	Assignments (fixed)	RUN, HOLD, RESET, ADV,	program No., CH1 operation cancel, CH2 operation cancel					
	Assignments (variable)	RAMP-E, FAST, AT, AUTO	MANUAL, G.Soak cancel, auto-load, O ² sensor check					
	Input sampling cycle							
	ON detection min. hold time	0.2 seconds (0.4 seconds f	or program No.)					
	Upper display	Green 5-digit, 7-segment LED This displays PV values in the basic display state. Item codes are displayed in the parameter setup.						
	Lower display	Orange 5-digit, 7-segment LED This displays SP and output % in the basic display state. Setting values are displayed in the parameter setup.						
	Program No. display	Green 2-digit, 7-segment LED This displays program No. in the basic display state.						
rammer	Segment No. display	Green 2-digit, 7-segment LED This displays segment No. in the basic display state. Item Nos. are displayed in parameter setup, and alarm No. is displayed when alarm occurs.						
ndication/programmer	Message display	This displays output graph, deviation graph, event state and tags in the basic display state. This displays reference messages in the parameter setup and program setup. This displays operation details and operation results of memory card operation.						
Indicat	Profile display	7 orange LEDs Displays program pattern rise, soak and fall trends.						
	Status displays	22 round LEDs Modes: RUN, HLD, MAN, PRG (green) Display details: PV, SP, OUT, TM, CYC, SYN, DEV (green), EG1, EG2 (red) Battery voltage: BAT (red) (blinks at low voltage) Status: AT (green)						
	Operation keys	18 rubber keys						
	Loader connector port	1 (dedicated cable with st	ereo miniplugs)					
8	Progrsm operation modes	READY: Ready to run program (control stop/program No. selectable) RUN: Program run HOLD: Program hold FAST: Program, fast-forward END: Program end READY FAST: Ready to run and fast-forward program						
Modes			ic operation operation (output can be controlled on console)					
	Constant-value operation modes	RUN: Program						
			tic operation operation (output can be controlled on console)					
	PID controls	Proportional band (P)	0.0 to 1000.0'% (0.0: ON-OFF control)					
e		Reset time (1)	0 to 3600 seconds. 0 seconds: PD control					
Controller		Rste time (D)	0 to 1200 seconds. 0 seconds: PI control					
Co		MV limit	Lower limit: -5.0 to upper limit % Upper limit: Lower limit to +105.0%					
		Manual reset	0.0 to 100.0%					

	PID controls	Number of PID sets	16 sets for program operation (9 segment unique sets + 7 sets for automatic zone selection)
		PID set selection	Segment designation/automatic zone selection can be switched by program operation.
Controller		MV change	0.1 to 110.0%/0.1 seconds
ontr		Auto-tuning	Automatic setting of PiD value by limit cycle system
ŏ		ON-OFF control	0 to 1000 U
	Direct/reverse	differential Possible	
	action switching		
	Auxiliary output	Output types	SP1, PV1, deviation 1, MV1, SP2, PV2, deviation 2, O ₂ sensor mV value
	Current output (CO)	Scaling	Possible
	Current output (SG) CH1, CH2	Output current: Allowable load resistar	4 to 20 mA dc nce: 600 ohm max. (under operating conditions)
	auxiliary outputs	Output accuracy:	±0.1%FS max. (under standard conditions)
	CH1, CH2	Output resolution: Max.output current:	1/10000 21.6 mA dc
		Min. output current:	2.4 mA dc
		Output updating cycle: Open terminai voitage:	0.1 seconds 25 V max.
ţs	Voltage output (6D)	Allowable load resistar	
Outputs	CH1, CH2	Load current adjustme	nt: 2 to 22 mA variable
õ		Variable open terminal OFF leakage current:	voltage: 25 V max. 100 PA max.
		Output response time:	At ON-OFF 600 Ω load: 0.5 ms max.
		Output resolution:	At OFF-ON 600 Ω load: 0.5 ms max. 1/1000
		Time-proportional cycle	
	Open-collector	External supply voltage	
	output (8D) CH1 CH2	Max. load current OFF leakage current:	100 mA/load 0.1 mA max.
	-	ON residual voltage:	2 V max.
		Output resolution: Time-proportional cycle	e: 1 to 240 seconds variable
	Open-collector	External supply voltage	
		Max. load current: Max. common current:	70 mA/load 500 mA
		OFF leakage current:	0.1 mA max.
		ON residual voltage	2 V max.
	Event types	PV type	PV, deviation, w/deviation standby, absoiute value deviation, w/ absoiul deviation standby, PV rate-of-change, SP, MV, G.Soak absolute valued
puts			w/G.Soak absolute value deviation standby, PV1 constant operation, PV2
out		Time type	constant operation Time events, RAMP-E time monitor, segment time, program time
Event out		Code type	Code event, code event w/ timer, program No. binary code, segment No. binary
ш			code, program No. BCD code, segment No. BCD code
		Mode type	Unique segment, RUN+HOLD+END+FAST, HOLD, READY+READY FAST, END G.Soak standby, MANUAL, AT executing, FAST+ READY FAST, console operation
			in progress, RUN, advance, all alarms, PV range alarm, controller alarm,
	Front boot on als	In case of DV time act	O₂ sensor error, low battery voltage
	Event hysteresis Event ON delay	In case of PV type set 0.0 to 3000.0 can be s	·
	RS-485	Network	Multidrop
			This controller is provided with only slave instrument functionality excep
			connected to ST221 (dedicated display device). 1 to 16 units max. (DIM)
			1 to 31 units max. (CMÁ, SCM)
su		Data flow	Half dupiex
atior		Synchronization	Start-stop synchronization
Communications		Transmission system	Balanced (differential)
n me		Data iine	Bit seriai
Con		Signal line	5 transmit/receive lines (3-wire connection also possible)
		Transmission	1200, 2400,4800, 9600 bps
		speed Transmission	500 m max. (totai)
		distance	(300 m max. for MA500 DIM connection)
		Other	Conforming to RS-485 interface specifications

	RS-485	Ch	ar. bit cou	int	11 bitc/	character					
	N3-103		rmat	111			tor 1 sta	t hit oo narity	and 2 ston hits		
			ta length		8 bits	bit, even parity, 1 stop bit; or 1 start bit, no parity, and 2 stop bits					
			lation		All inputs and outputs are completely isolated except external switch inputs.						
	RS-485 communio			ormed by		ng to a computer equipp					
				•		· · · · ·					
	RS-232C	_	twork ta flow		1:1 Con Half dur		s provide	d with only sla	ve instrument functionality.		
s			nchroniza	tion		op synchronization					
tion		- /	insmissio			iced type					
lica			stem	•	ensulai	ioou iypo					
2		ta iine		Bit seria	al						
Communications		Sig	anal line		3 transf	nit/receive lines					
0			ansmissio eed	n	1200, 24	400, 4800, 9600 bps					
		Tra	ansmissio stance	n	15 m m	ax.					
		Ot	her		Conform	ning to RS-232C interfac	ce specific	cations			
		Ch	ar. bit co	unt	11 bits/	/character					
			rmat		6	bit, even parity, 1 stop bit	; or 1 sta	rt bit, no paritv	and 2 stop bits		
			ta length		8 bits	to and autouts are activ		lated evec + -	tornal awitch innut-		
	Program PiD va					ts and outputs are comp ent) and other data can l					
	(sold separately)	•	unicicity (02101,1					and nom memory bara		
	Save (SAVE)	Functior	n for copy	ing DCP5	52 data to	o memory card.					
	Load (LOAD)			ng memo	ry card d	ata to DCP552.					
	Memory card (so	· · ·	• /								
	Model No.		ту Туре		(bytes)	Number of Programs		Replacement	Parameters		
P	SKM008A SKM018A		AM AM		00 K 50 K	Max. 10 Max. 26		possible possible	Setup data Variable parameters		
Memory card	SKM018A SKM064A		RAM		75 K	Max. 20		possible	PID parameters		
D D E	eranee ht				••••			peccipic	Event configuration data		
Me									Constant-value operation		
									data		
	-		-			Imber of segments) + (5x number of sub-functions). Ip data: 217 bytes (17+2x100)					
	• Number of byte	es per pa	rameter		up data: iable para		•	,			
						ers+ constant-value ope	ration da	ta:			
				Ev	ent confi	565 by iguration data: 209 by		+2x2x8x16+ 2x3x32)	2x2x9)		
	Memory backup	р	Memory			ed up RAM	,	,			
			Battery i			wer OFF: Approx. 5 yea					
	Rated power vo	ltage	100 to 2		50/60 Hz	troller power ON: Approx. 10 years under standard conditions					
	Power consum		25 VA m		00,00112						
	Power ON rush	n current	50A ma	х.							
	Power ON oper	ation		me: 10 se	econds max. (time until normal operation is possible under normal operating condi-						
ø	Allowable trans	siont	tions)	aax (und	er operating conditions)						
General specifications	power loss	Sient	20 115 1	iax. (unu	er operati	ng conunions)					
ifice	Insulation resis	stance	Min. 50	$M\Omega$ acro	oss powe	r terminal 39 or 40 and	FG termi	nal 52 or 53 (l	oy 500V dc megger)		
l a	Dielectric stren	igth				inute between power te					
ral s						d secondary side capac hen carrying out a withst					
l de Ca				grounded	l seconda	ry side terminals (e.g. w	hen grou	nding type the	mocouple is used) from tha		
Ō						the test is carried out with the wiring as it is, this might result in malfunction,					
	Standard cond	itions		t tempe		23±2°C					
				t humid bower vo		60±5%RH 105V ac±1%					
				frequence	•	50±1 Hz, or 60±1 Hz					
				on resist	•	0 m/s ²					
				resistan		0 m/s ²					
			Moun	ting a	ngle	Reference plane (verti	cal)±3°				

	Operating conditions	Ambient tempera	ture range	O to 50°C (ambient temperature at the bottom side of case when gang-mounted)					
		Ambient humidity range		10 to 90%RH (condensation not allowed)					
		Rated power volt	age	100 to 24	40V ac				
		Allowable power	voltage	90 to 264	IV ac				
		Power frequency		50±2 Hz,	or 60±2 Hz				
		Vibration resista	nce	0 to 1.96	m/s²				
su		Shock resistance)	0 to 9.80	m/s²				
General specifications		Mounting angle		Referenc	e plane (vertical) ±10 degree	es			
lfic	Transport/storage	Ambient tempera	ture range	-20 to +7	′0°C				
bec	conditions	Ambient humidity	/ range	10 to 95	%RH (condensation not allo	wed)			
s le		Vibration resistance		O to 4.90	m/s ² (1 O to 60 Hz for 2 hor	urs each in X, Y and	Z directions)		
neri		Shock resistance		O to 490 m/s ² (3 times vertically)					
Gel		Package drop tes	st	Drop height: 60 cm (1 angle, 3 edges and 6 planes; free fall)					
	Terminal ecrew	M3.5 self-tapping	screws						
	Terminal screw tightening torque	0.76 to 0.98 N⋅m							
	Mask/case materials	Mask Multilon		Case: Multilon					
	Mask/case color	Mask: Dark gray	Munsell 5Y3.	.5/1) Case: Light gray (Munsell 2.5Y7.5/1)					
	Installation	Specially designed	dmountina b	racket					
	Weight	Approx. 1.5 kg							
	Item	Model No.	Q'tv		Item	Model No.	Q'ty		
P ë	Unit indicating label	—	1		Soft dust-proof cover	61446141-001	_		
Standard accessories	Mounting bracket	81446044-001	1 set (2 p'ce	es) <u>a</u> (26	eet				
Sta Sta	User's Manual	CP-UM-5017E	1	pari	Lithium battery set	81448140-001	Approx. 200 g		
ā				Auxiliary parts sold separately)	Memory csrd (RAM, battery replace-	SKMO08A SKM016A	Approx. 30 g		
				Auxi (sold	ment not possible)	SKM064A			

Table 1 Input Types and Ranges (selectable in setup)

• Thermocouple

Inj	out Typ	e	Input Ra	nge (FS)	Accuracy (under standard conditions)		
Symbol	Code	Range No.	°C	"F	Accuracy (under standard conditions)		
K (CA)	K46	16	-200.0 to +200.0	-300.0 to +400.0	±0.1%FS		
K (CA)	K09	0	0.0 to 1200.0	0 to 2400	±0.1%FS		
K (CA)	K08	1	0.0 to 800.0	0 to 1600	±0.1%FS		
K (CA)	K04	2	0.0 to 400.0	0 to 750	±0.1%FS		
E(CRC) -	E08	3	0.0 to 800.0	0 to 1800	±0.1%FS		
J (IC)	J08	4	0.0 to 800.0	0.0 to 1600	±0.1%FS		
T (CC)	T44	5	-200.0 to+300.0	-300 to +700	±0.1%FS	±0.3%FS between -200°C to -45°C	
B (PR30-6)	B18	6	0.0 to 1800.0	0 to 3300	±0.1%FS	±4.0%FS between 0 to 260°C,±0.15%FS between 260 to 800°C	
R (PR13)	R16	7	0.0 to 1600.0	0 to 3100	±0.1%FS		
S (PR1 O)	S16	8	0.0 to 1600.0	0 to 3100	±0.1%FS		
W (WRe5-26)	W23	9	0.0 to 2300.0	0 to 4200	±0.1%FS		
W (WRe5-26)	W14	10	0.0 to 1400.0	0 to 2552	±0.1%FS		
PR40-20	D19	11	0.0 to 1900.0	0 to 3400	±0.2%FS	±0.9%FS between 0 to 300°C,±0.5%FS between 300 to 800°C	
N	U13	12	0.0 to 1300.0	32 to 2372	±0.1%FS		
PLII	Y13	13	0.0 to 1300.0	32 to 2372	±0.1%FS		
Ni-Ni-Mo	Z13	14	0.0 to 1300.0	32 to 2372	±0.1%FS		
Golden iron chromel	206	15	0.0 to 300.0	K (K: Kelvin)	±0.4%FS		

• Resistance temperature detector (RTD)

In	out Type	9	Input Ra	nge (FS)	Accuracy (under standard conditions)	
Symbol	Code	Range No.	°C	۴F	Accuracy (under standard conditions)	
JIS'89Pt100	F50	64	-200.0 to +500.0	-300.0 to +900.0	±0.1%FS	
(IEC Pt100 Ω)	F46	65	-200.0 to +200.0	-300.0 to +400.0	±0.1%FS	
	F32	66	-100.0 to +150.0	-150.0 to +300.0	±0.1%FS	
	F36	67	-50.0 to +200.0	-50.0 to +400.0	±0.1%FS	
	F33	68	-40.0 to +60.0	-40.0 to +140.0	±0.15%FS	
	F01	69	0,0 to 100.0	0.0 to 200.0	±0. 15%FS	
	F03	70	0.0 to 300.0	0.0 to 500.0	±0.1%FS	
	F05	71	0,0 to 500.0	0.0 to 900.0	±0.1%FS	
JIS'89JPt100	P50	96	-200.0 to +500.0	-300.0 to +900.0	±0.1%FS	
	P46	97	-200.0 to +200.0	-300.0 to +400.0	±0.1%FS	
	P32	98	-100.0 to +150.0	-150,0 to +300.0	±0.1%FS	
	P36	99	-50.0 to +200.0	-50.0 to +400.0	±0.1%FS	
	P33	100	-40.0 to +60.0	-40.0 to +140.0	±0.15%FS	
	Pol	101	0.0 to 100.0	0.0 to 200.0	±0.15%FS	
	P03	102	0.0 to 300.0	0.0 to 500,0	±0.1%FS	
	P05	103	0,0 to 500.0	0.0 to 900,0	±0.1%FS	

• DC current, DC voltage

Input Type				Innut Dange (EC)	Accuracy (under standard conditions)		
Symbol	Code	Range No.		Input Range (FS)	Accuracy (under standard conditions)		
mA (linear)	C01	48	4 to 20 mA	Programmable range	±0.1%FS		
IIIA (IIIeal)	A (linear) 251 52 2.4 to 20 mA Programmable range -19999 to +20000		-19999 to +20000	±0.1%FS			
	MO1	49	0 to 10 mV	(decimal point position can be	±0.1%FS		
mV (linear)	L02	50	-10 to +10 mV	changed)	±0.1%FS		
	—	51	0 to 100 mV		±0.15%FS		
mA (linear)	C01	128	4 to 20 mA	Programmable range	±0.15%FS		
IIIA (IIIear)	Z51	134	2.4 to 20 mA	-19999 to +20000	±0.1%FS		
	—	129	0 to 1 V	(decimal point position can be	±0.1%FS		
		130	-1 to + 1 V	changed)	±0.1%FS		
V (linear)	Vol	131	1 to 5 V		±0.1%FS		
	—	132	0 to 5V		±0.1%FS		
	—	133	0 to 10 V		±0.1%FS		
O ₂ sensor*	—	135	0 to 1250 mV		±0.1%FS	When converted to mV value	
			Carbon potential (CP value) indication range: 0.000 to 4.000%C (Note that PID control is calculated in input range 0.000 to 2.000% C.) O ₂ partial pressure (PO ₂) indication range: 0.000 to 1.500 x 10-20 atm				

 Any O₂ sensor made by Marathon Monitors, Cambridge, Corning, AACC (Advanced Atmosphere Control Corporation), and Furnace Control can be used.

• PV2 is fixed for the O2 sensor in the case of models supporting carbon potential,

! Handling Precautions

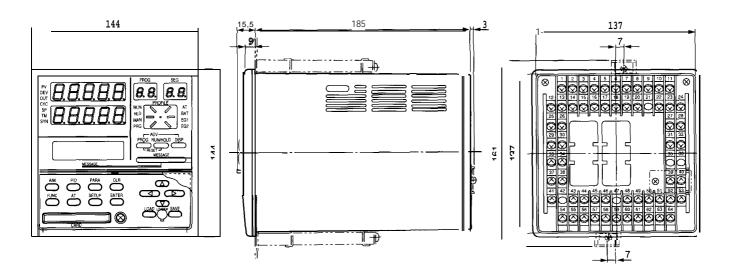
- The unit of code Z06 is Kelvin (K).
- The PV lower limit alarm does not occur with codes F50 and P50.
- The number of digits past the decimal point for DC current and DC voltage is programmable within the range 0 to 4.
- The PV upper limit alarm is output by the O_2 sensor when the voltage exceeds 1375 mV. The PV lower limit alarm, however, is not output.

MODEL SELECTION GUIDE

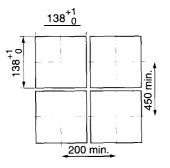
Key # - I - II - III - IV - V

	I	II	III	IV	v	
Key No.	_	Number of PV inputs	Carbon Potential	Option	Additions	Specifications
DCP552						Digital Programmable Controller (2-loop model)
	E					Universal Output
		2				Two Inputs
			0			None
			1			Oxygen Sensor Input for Carbon Potential
				0		None
				1		1 Auxiliary output
				2		2 Auxiliary outputs, Communications
					00	None

EXTERNAL DIMENSIONS



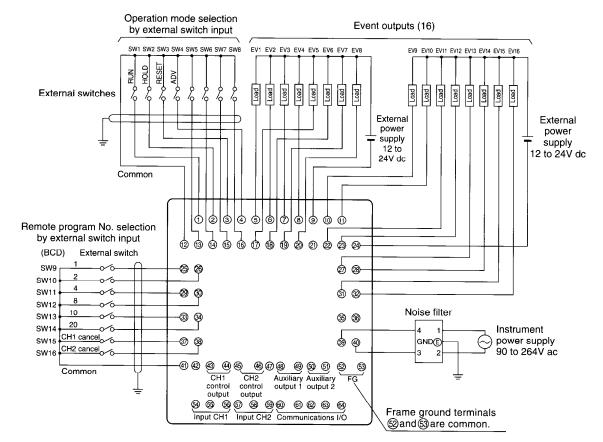
PANEL CUTOUT



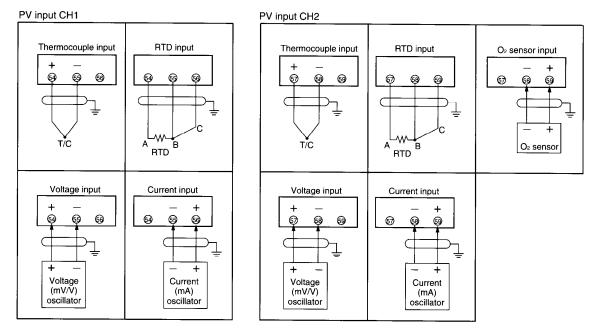
(Unit: mm)

(Unit: mm)

8



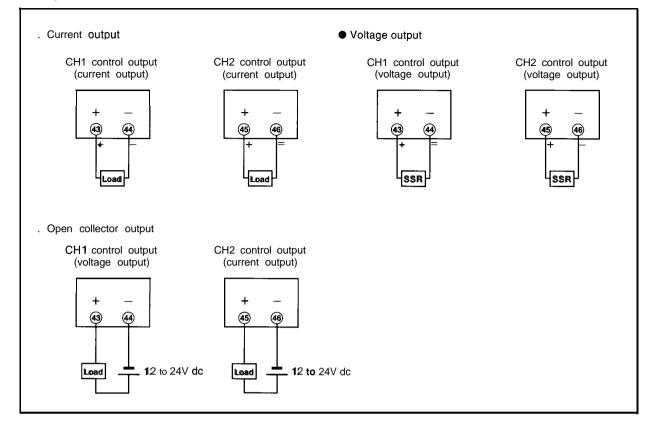
Input



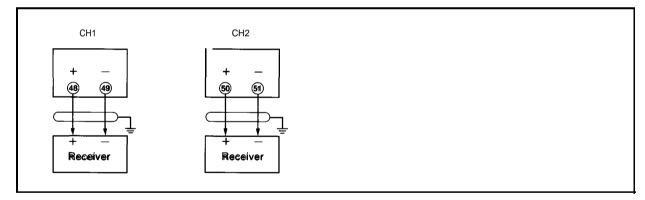
Note: If voltage mode signals are input to PV input CH1 (terminal Nos. (5), (6)) and input CH2 (terminal Nos. (3), (9)) for current input by mistake, a large current might flow and cause the controller to malfunction. Before wiring to the current input terminals on the **DCP552**, make sure that current input signals are output correctly within the range 4 to 20 mA.

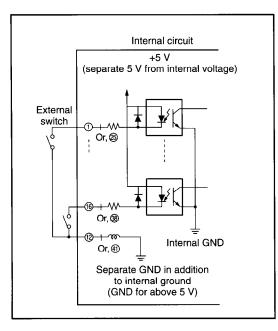
CONTROL OUTPUT AND AUXILIARY OUTPUT

Control output

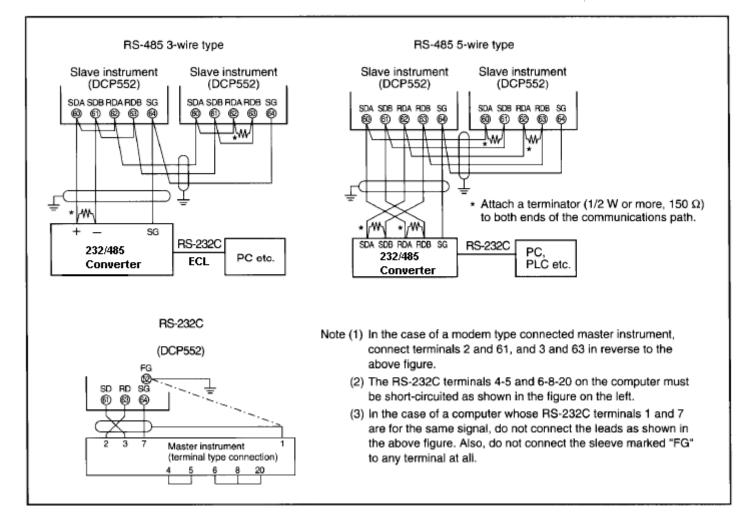


Auxiliary output





COMMUNICATIONS I/O (OPTION)



WIRING PRECAUTIONS

1. Isolating Inputs and Outputs Inside the Controller

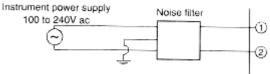
Solid lines ——— show isolated items. Dotted lines - - - - - show non-isolated items.

PV input CH1		Control output CH1	
PV input CH2		Auxiliary output CH1	
Loader communications	Digital circuit	Control output CH2	
External switch input	Digital circuit	Auxiliary output CH2	
Communications		Event output	
Memory card input		Event output	

2. Noise Countermeasures for Instrument Power Supplies

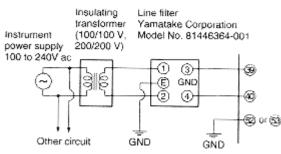
(1) Reducing noise

Connect the DCP552 to a single-phase power supply for instruments, and take measures to prevent the influence of electrical noise.



(2) When there is a lot of noise

If there is a lot of electrical noise, we recommend inserting an insulating transformer in the power circuit and using a line filter.



3. Noise Generating Sources and Countermeasures

Generally, the following generate electrical noise:

Relays and contacts, electromagnetic coils, solenoid valves, power lines (in particular, 90 Vac min.) induction loads, inverters, motor

WARRANTY / REMEDY

Honeywell warrants goods of its manufacture as being free of defective materials and faulty workmanship. Contact your local sales office for warranty information. If warranted goods are returned to Honeywell during the period of coverage, Honeywell will repair or replace without charge those items it finds defective. The foregoing is Buyer's sole remedy and is in lieu of all other warranties, expressed or implied, including those of merchantability commutators, phase angle control SCR, radio communications equipment, welding equipment, high-voltage ignition equipment.

(1) Fast-rising noise

CR filters are effective in countering fast-rising noise.

Recommended CR filter: Yamatake Corporation Model No. 81446365-001

(2) Noise with a high wave height

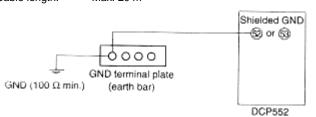
Varisters are effective in countering noise with a high wave height. However, note that the varister may become short-circuited when trouble occurs. Pay attention to this when providing a varister on a controller.

Recommended varister:

Yamatake Corporation Model No. 81446366-001 (for 100 Vac) 81446367-001 (for 200 Vac)

4. Ground

Use only the FG terminal 52 or 53 on the DCP552 for grounding. Do not ground across other terminals. When it is difficult to ground shielded cable, prepare a separate GND terminal plate (earth bar).



5. Precautions During Wiring

- (1) After providing anti-noise measures, do not bundle primary and secondary power leads together, or pass them through the same piping or wiring duct.
- (2) Maintain a distance of at least 50 cm between I/O signal leads or communications leads and the power lead. Also, do not pass these leads through the same piping or wiring duct.

6. Inspection After Wiring

After wiring is completed, be sure to inspect and check the wiring state. Wrong wiring may cause controller malfunction or accidents.

and fitness for a particular purpose. Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this printing. However, we assume no responsibility for its use.

While we provide application assistance personally, through our literature and the Honeywell web site, it is up to the customer to determine the suitability of the product in the application.



Sensing and Control

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