## I PC5000 S/ D

## Universal Programmer

## Ovenview

The IPC5000 is a high-functional Single or Dual loop programmer retaining all the reliability, simplicity, and compatibility. This programmer is operated by touchscreen in 5.7 inch LCD monitors and controls in various kinds of applications such as:

- Furnace \& Industrial Oven
- Autoclave
- Test Chamber
- Environmental Room / Clean Room
- Retort Oven
- Pressure Cooker
- Dyeing Machine
- Reactor


## Features

## - 5.7 inch LCD Touch Screen

Configuration \& operation will be done by touch screen function keys in LCD display.

## - Universal I nput(s)

Analog input(s) is a low-level type (s), which accepts Thermocouple, RTD, mA, voltage type. (See Table 1)

- 0.1\% Input Accuracy

Analog input(s) has typical accuracy of $\pm$ $0.1 \%$ of full-scale input.

- 12 DIs/ 12 Dos

12 points of digital inputs can be connected to non-voltage contact (relay contact) or open collector (sink current toward 0 V ), and they are allocated to predefined actions. 12 digital outputs can be

assigned to 4 different types of events (MODE, Alarm, Time and PV)

- 100 Programs, 2000 segments

100 Programs can be programmed within 100 segments for each and 2000 segments in total. 10 Links are offered, and each Link can link up to 6 programs.

## - Heat/ Cool Capability

Each control loop provides split range control with independent PID tuning constants - one for heating, one for cooling - plus mixed output forms.

## - Ethernet Communication

A communication link is provided between IPC5000 and a host computer or PLC via RS-485 (Modbus® RTU) or Ethernet (Modbus TCP) communications option.

## - I P65 Front Face Protection

IP65 rated front face permits use in applications where it may be subjected to
moisture, dust conditions.

## - Asynchronous/ Synchronous Mode

In Dual-Channel type, two loop controls can be run independently with different program and also they can be operated simultaneously with one single program.

## - Multi-Language Prompts

3 different languages will be selected via configuration and displayed.

## - PC Configuration

A free-ware will be offered and IPC5000 can be configured and operated thru this software on PC.

## - Real Time Clock

IPC5000 provides accurate time and makes it possible to schedule running operation.

## - Program data changeable

In RUN mode, the program data are changeable.

Honeywell

| Spec ific ations |  |  |  |
| :---: | :---: | :---: | :---: |
| Model |  | IPC5000S | IPC5000D |
| Display |  |  |  |
| Digital Indication \& Display | Display Type | 5.7 inch LCD (STN Negative, Blue) |  |
|  | Screen Size <br> (Unit: mm/inch) | $\frac{115.17}{4.534}(W) \times \frac{86.37}{3.4}(H)$ |  |
|  | Resolution | 320(W) x 240(H) |  |
|  | Back Light | LED, White (Luminous Intensity: $20 \mathrm{~cd} / \mathrm{m}^{2}$ ) |  |
|  | Display Size | 40 lines x 30 lines (8x8 dots characters) |  |
|  | Display Color | Blue characters on white background |  |
|  | Display Language Cap. | Up to 3 languages |  |
|  | Operation | Analog touch panel (Actuation force: $10 \mathrm{~g}-80 \mathrm{~g}$ ) |  |
| General |  |  |  |
| Rated Power Supply Voltage |  | 100 to 240 V AC $50 / 60 \mathrm{~Hz}$, 37VA Max. |  |
| Inrush Current when power supply turns on |  | Lower than 50 A |  |
| Insulation Resistance |  | Higher than 50Ms under DC 500V megger during power terminal and PE terminal |  |
| Withstand Voltage |  | 1500 V AC $50 / 60 \mathrm{~Hz}$ for 1 min across power terminal and PE terminal |  |
| Reference | Ambient Temperature | $23 \pm 2{ }^{\circ} \mathrm{C}$ |  |
|  | Relative Humidity | $60 \pm 5 \% \mathrm{RH}$ |  |
|  | Power Voltage (Vac) | 110 V AC |  |
|  | Power Frequency | $50 \pm 1 \mathrm{~Hz}$ or $60 \pm 1 \mathrm{HZ}$ |  |
|  | Vibration Resistance | $0 \mathrm{~m} / \mathrm{s}^{2}$ |  |
| Operative Limits | Ambient Temperature | $0 \text { to } 50^{\circ} \mathrm{C}$ |  |
|  | Relative Humidity | 10 to $90 \%$ RH (non-condensing) |  |
|  | Power Voltage (Vac) | 85 to 264V AC |  |
|  | Power Frequency | $50 \pm 2 \mathrm{~Hz} \text { or } 60 \pm 2 \mathrm{~Hz}$ |  |
|  | Vibration Resistance | 0 to $1.96 \mathrm{~m} / \mathrm{s}^{2}$ ( 10 to 60 Hz in $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ directions for 2 hours each) |  |
| Transportation \& Storage | Ambient temperature | $-20 \text { to }+70^{\circ} \mathrm{C}$ |  |
|  | Relative Humidity | $10 \text { to +95\% RH (non-condensing) }$ |  |
|  | Vibration Resistance | 0 to $1.96 \mathrm{~m} / \mathrm{s}^{2}$ ( 10 to 60 Hz in $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ directions for 2 hours each) |  |
| Exterior |  | Case and front panel: plastic |  |
| Mounting |  | Panel-mount |  |
| Exterior Size (unit: $\frac{m m}{\text { inch }}$ ) |  | $\frac{196}{7.717}(W) \times \frac{131}{5.157}(H) \times \frac{154}{6.063}(D)$ |  |
| Panel Cutout (unit: $\frac{m m}{\text { inch }}$ ) |  | $\frac{185.5}{7.303} \frac{ \pm 0.5}{ \pm 0.02}(W) \times \frac{120.5}{4.744} \frac{ \pm 0.5}{ \pm 0.02}(H)$ |  |

Honeywell

| Spec ific ations |  |  |  |
| :---: | :---: | :---: | :---: |
| Model |  | IPC5000S | IPC5000D |
| Input \& Output |  |  |  |
| Analog Input | Number of point | 1 point (Universal input) | 2 points (Universal input) |
|  | Type | TC $: K, J, R, S, B, E, T, N(J I S / I E C), W, C$ <br> RTD $:$ Pt100 (JIS/IEC), JPt100 (JIS) <br> Linear $:$ VOLTAGE $0 \sim 10 V, 0 \sim 5 \mathrm{~V}, 1 \sim 5 \mathrm{~V}$ <br>  CURRENT $0 \sim 20 \mathrm{~mA}, 4 \sim 20 \mathrm{~mA}$ <br> (For details, refer to Table 1-1) |  |
|  | Sampling Rate | 100 ms |  |
|  | Indication Accuracy | $\pm 0.1 \% \mathrm{FS} \pm 1$ digit (Accuracy is variable according to input type or range) |  |
|  | Cold junction accuracy | $\pm 1.0{ }^{\circ} \mathrm{C}$ ( under standard conditions) |  |
|  | Input bias | -99.9 ~ +99.9 variable |  |
|  | Digital filter | $0 \sim 120 \sec$ (0: filter off) |  |
|  | Square-root Extraction | Low-cut: 0.1~5.0\% of input <br> (in case of voltage input from orifice or pressure sensor) |  |
|  | Compensation | Linearity / Approximation <br> (1) Segment break-point: 1 to 10 of total range <br> (2) Linearity <br> Bias : -10000.0~10000.0 <br> Compensation Set : -5.0~105.0\% of input range span <br> (3) Approximation <br> Bias: -5.0~105.0\% of input range span <br> Compensation Set : -5.0~105.0\% of input range span |  |
| Analog Output <br> (Transmission output) <br> : Optional | Object | PV1, SP1, MV1, DEV1 | PV1, SP1, MV1, PV2, SP2, MV2, DEV 1/ 2 |
|  | Output type | 4~20mA DC |  |
|  | Output accuracy | +/- $0.1 \%$ of span |  |
|  | Update Rate | 100 ms |  |
| Digital Inputs <br> (External switch input) | Number of point | 12 points |  |
|  | Connectable type | No-Voltage contact (relay contact) <br> Open collector (sink current toward OV) |  |
|  | Allocation (Fixed) | RUN/STOP, HOLD, ADV, Trouble inputs, Program number <br> (For details, refer to Table 1-2) |  |
|  | Trouble input | 4 points | 2 points |
|  | Trouble message | 32 messages (Each trouble can have its message), Max. 22 characters |  |
|  | Sampling cycle | 100 ms |  |

Honeywell

## Spec ifications

\section*{| Mod |  |
| :--- | :---: |
| I nput \& Output |  |}


| Digital Output (Event Output) | Number of point |  | 12 points |
| :---: | :---: | :---: | :---: |
|  | Output Type |  | Open collector |
|  | External supply voltage |  | MAX DC30V |
|  | Max. load current |  | MAX $100 \mathrm{~mA} / 1 \mathrm{ch}$ |
|  | Time Event |  |  |
|  | Event Code |  | Code 0 (OFF), Code 1 (ON), Code 2 (On-Delay \& Cut-Back) |
|  | Object |  | Segment Time |
|  | PV Event |  |  |
|  | Event code |  | Code 11 - Code 38 |
|  | Object |  | Set Point (SP) / Process Variable(PV) <br> Destination(Target) Value (DV) / Manipulated value (MV) |
|  | Operating point |  | Absolute value (ABS) / Deviation (DEV) / MAX, MIN value |
|  | Operating Condition |  | Band/ LOW/HIGH |
|  | Range | Absolute | -19999.0~20000.0 Unit |
|  |  | Deviation | -19999.0~20000.0 Unit |
|  |  | Differential | $0 \sim 1000.0$ Unit |
|  | On delay time |  | 0 ~ 99 sec |
|  | Mode Event |  |  |
|  | Event code |  | Code 41 - Code 60 |
|  | Object |  | RUN, HOLD, ADV, WAIT, MAN, TUNE, READY, FIX, STOP, END, TRBL, DOWN, UP |
|  | Alarm Event |  |  |
|  | Event Code |  | Code 61 - Code 80 |
|  | Object |  | INNER : Object = PV, SP, DV, MV <br>  Operating point = ABS, DEV, MAX \& MIN value <br>  Operating condition = Band/LOW/HIGH <br> Range $:$ Same with PV Event <br> DIAGNOSIS $: ~ P V ~ i n p u t ~ b u r n-o u t ~$  <br> FAIL $:$ Instrument fail (Type: Memory, Power failure) |
|  | Action |  | RUN: Operation in RUN mode <br> ALL: Operation in all cases |
| Auxiliary Analog Input <br> : Optional | Number of point |  | 1 point |
|  | Input type |  | $\mathrm{mA}(4 \sim 20 \mathrm{~mA}), \mathrm{V}(0 \sim 10 \mathrm{~V}, 1 \sim 5 \mathrm{~V})$ |
|  | Sampling Rate |  | 200 ms |
|  | Input accuracy |  | $\pm 0.3 \% \mathrm{FS} \pm 1$ digit |

[^0]

Honeywell

| Spec ific ations |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Model |  |  | IPC5000S | IPC5000D |
| Control |  |  |  |  |
| PID |  | Algorithm | PID-A / PID-B / DUP-A / DUP-B |  |
|  |  | Proportional Band (P) | Proportional Band: 0.1 ~ 9999\% GAIN: 0.001 ~ 1000 |  |
|  |  | Integral Time (1) | $0.00 \sim 10.00 \mathrm{~min}$ |  |
|  |  | Derivative Time (D) | $0.02 \sim 50.00 \mathrm{~min}$ |  |
|  |  | Manipulated Value Limit (MV) | Low-limit: -5.0 to High-limit\% <br> High-limit: Low-limit to $+105.0 \%$ |  |
|  |  | Manual Reset | -100 to +100 |  |
|  |  | Maximum PID groups | 8 groups | Loop 1:0 groups, 8 groups <br> Loop 2 : 0 groups, 8 groups |
|  |  | PID Group Selection | Segment specified, Automatic zone selectable during program run |  |
|  |  | Auto Tuning | Accutune II: Automatic setting of PID value by limit cycle method. |  |
|  |  | Fuzzy Control Function | Fuzzy Control function |  |
|  |  | On-off Control Diff. | $0 \sim 1000$ |  |
| Control Direction |  |  | Selection is settable (Direct/Reverse) |  |
| HEAT/COOL Control |  |  | HEAT/COOL available | HEAT/COOL available for each CH |
| Operation Mode |  |  | Auto/Manual operation is switcheable <br> *Manual Output: <br> i) Bumpless <br> ii) Preset value: -5.0~105.0\% |  |
| Output | Output Set | TYPE | Provided with 9 types (refer to Table1-3) |  |
|  |  | Signals | 4~20mA DC |  |
|  | Current | Accuracy | +/-0.1\% of span |  |
|  |  | Update cycle | 100 msec |  |
|  | Voltage <br> Pulse | Open Time <br> Terminal Voltage | Lower than 15V DC (20mA) |  |
|  |  | Time Proportional Cycle | 1 ~ 240 sec |  |
|  | Relay | Signal | NC, NO, and common terminals (SPDT) |  |
|  |  | Contact Rating | 250VAC, 3A or 30VDC, 3A (Resistance load) |  |
|  | Open | External <br> Supply Voltage | MAX DC30V |  |
|  |  | Max. Load Current | MAX $100 \mathrm{~mA} / 1 \mathrm{ch}$ |  |

Honeywell

| Spec ifications |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Model |  |  | IPC5000S |  | IPC500 |
| Control Operation |  |  |  |  |  |
| Program | READY |  | Stand-by status before program start (Control stop) |  |  |
|  | RUN |  | Program running status <br> * Program Start <br> Quick Start by RUN/STOP key or external contact relay input <br> Timer Start by scheduled time |  |  |
|  | HOLD |  | Status to hold program run by force |  |  |
|  | WAIT |  | Waiting status during the WAIT function enabled |  |  |
|  | END |  | Status after program completed (Control stop) |  |  |
|  | BREAK |  | POWER FAILURE or Stop status (Control stop) |  |  |
|  | TUNE |  | AUTO-TUNING status |  |  |
| Fix Control |  |  | Stand-by status before program start (Control stop) |  |  |
|  | RUN |  | Program running status <br> * Program Start <br> Quick Start by RUN/STOP key or external contact relay input <br> Timer Start by scheduled time |  |  |
|  | HOLD |  | Status to hold program run by force |  |  |
|  | tune |  | AUTO-TUNING status |  |  |
| Communication |  |  |  |  |  |
| Communication | $\begin{aligned} & \text { RS-232 } \\ & \text { (Basic) } \end{aligned}$ | Speed | 9600 or 19200 |  |  |
|  |  | Parity check | NONE |  |  |
|  |  | Bit length | 8 |  |  |
|  |  | Stop Bits | 1 |  |  |
|  | RS-485 <br> (Option) | Data Bits per Character | Bit transfer order | LSB |  |
|  |  |  | End of message |  | acters |
|  |  | Protocol | Modbus TCP |  |  |
|  |  | Port | One 10Base-T(RJ- | nnecto |  |
|  |  | Cabling Type | UTP category 2 or Note) UTP: Unshie | wiste |  |

Honeywell
Table 1 - Input Actuations

| I nput type |  | I nput Code | Range |  | Measurement Accuracy |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\bigcirc$ | OF |  |  |
| Thermocouples | K (CA) |  | K1 | -200.0~200.0 | -328.0~392.0 | +/-0.1\% FS | Below $0 \bigcirc \mathrm{C}:+/-0.2 \% \mathrm{FS}$ |
|  |  | K2 | $0.0 \sim 1200.0$ | 32.0~2192.0 | +/-0.1\% FS |  |
|  |  | K3 | 0.0~800.0 | 32.0~1472.0 | +/-0.1\% FS |  |  |
|  |  | K4 | 0.0~400.0 | 32.0~752.0 | +/-0.1\% FS |  |  |
|  | $J$ (IC) | J | 0.0~800.0 | 32.0~1472.0 | +/-0.1\% FS |  |  |
|  | R | R | 0.0~1600.0 | 32.0~2912.0 | +/-0.1\% FS |  |  |
|  | S | S | 0.0~1600.0 | 32.0~2912.0 | +/-0.1\% FS |  |  |
|  | B | B | 0.0~1800.0 | 32.0~3272.0 | +/-0.1\% FS | $+/-4.0 \%$ FS at 0 to $260 \circ$ C <br> $+/-0.15 \% \mathrm{FS}$ at 260 to $800{ }^{\circ} \mathrm{C}$ |  |
|  | E (CRC) | E | 0.0~800.0 | 32.0~1472.0 | +/-0.1\% FS |  |  |
|  | T (CC) | T | -200.0~300.0 | -328~572 | +/-0.1\% FS | $+/-0.3 \% \mathrm{FS}$ at -200 to -450 C |  |
|  | N | N | 0.0~1300.0 | 32~2372 | +/-0.1\% FS |  |  |
|  | W | W1 | 0.0~1200.0 | 32~2192 | +/-0.1\% FS |  |  |
|  |  | W2 | 0.0~2300.0 | 32~4172 | +/-0.1\% FS |  |  |
|  | C | C | 0.0~2300.0 | 32~4172 | +/-0.1\% FS |  |  |
| RTD | Pt100 <br> (JIS/IEC) | Pt1 | -200.0~500.0 | -328.0~932.0 | +/-0.1\% FS |  |  |
|  |  | Pt2 | -200.0~200.0 | -328.0~392.0 | $+/-0.1 \% \mathrm{FS}$ |  |  |
|  |  | Pt3 | -100.0~150.0 | -148.0~302.0 | +/-0.1\% FS |  |  |
|  |  | Pt4 | -50.0~200.0 | -58.0~392.0 | +/-0.1\% FS |  |  |
|  |  | Pt5 | -40.0~60.0 | -40.0~140.0 | +/-0.2\% FS |  |  |
|  |  | Pt6 | 0.0~100.0 | 32.0~212.0 | +/-0.2\% FS |  |  |
|  |  | Pt7 | 0.0~300.0 | 32.0~572.0 | +/-0.1\% FS |  |  |
|  |  | Pt8 | 0.0~500.0 | 32.0~932.0 | +/-0.1\% FS |  |  |
|  | JPt100 (JIS) | JPt1 | -200.0~500.0 | -328.0~932.0 | +/-0.1\% FS |  |  |
|  |  | JPt2 | -200.0~200.0 | -328.0~392.0 | +/-0.1\% FS |  |  |
|  |  | JPt3 | -100.0~150.0 | -148.0~302.0 | +/-0.1\% FS |  |  |
|  |  | JPt4 | -50.0~200.0 | -58.0~392.0 | +/-0.1\% FS |  |  |
|  |  | JPt5 | -40.0~60.0 | -40.0~140.0 | +/-0.2\% FS |  |  |
|  |  | JPt6 | 0.0~100.0 | 32.0~212.0 | +/-0.2\% FS |  |  |
|  |  | JPt7 | 0.0~300.0 | 32.0~572.0 | +/-0.1\% FS |  |  |
|  |  | JPt8 | 0.0~500.0 | 32.0~932.0 | +/-0.1\% FS |  |  |
| DC Voltage | 0~10V | DCV1 | Configurable Range -19999~20000 <br> (DP position is configurable) |  | +/-0.1\% FS |  |  |
|  | 0~5V | DCV2 |  |  | +/-0.1\% FS |  |  |
|  | 1~5V | DCV3 |  |  | +/-0.1\% FS |  |  |
| DC Current | $0 \sim 20 \mathrm{~mA}$ | MA1 |  |  | +/-0.1\% FS |  |  |
|  | 4~20mA | MA2 |  |  | +/-0.1\% FS |  |  |

Honeywell
Table 2 - The Function Table of Extemal Switch Input (Digital Input)

| DI No. | Function | Detection way |
| :--- | :--- | :--- |
| DI 01 | RUN/STOP (RUN $\leftarrow \rightarrow$ STOP) | Leading edge |
| DI 02 | HOLD | ON status |
| DI 03 | ADV | Leading edge |
| DI 04 | Trouble Message Input 1 | ON status |
| DI 05 | Trouble Message Input 2 | ON status |

- IPC5000 Single Channel Type

| DI No. | Function | Detection way |
| :--- | :--- | :--- |
| DI 06 | Trouble Message Input 3 | ON status |
| DI 07 | Trouble Message Input 4 | ON status |

- IPC5000 Dual Channel Type

| DI 06 | DI 07 | Channel Selection |
| :---: | :---: | :--- |
| OFF | OFF | Both CH1 and CH2 Disabled |
| OFF | ON | CH1 Disabled, but CH2 Enabled |
| ON | OFF | CH1 Enabled, but CH2 Disabled |
| ON | ON | Both CH1 and CH2 Enabled |

- Program Selection

| DI 08 | DI 09 | DI 10 | DI 11 | DI 12 | Pattern Selection |
| :---: | :---: | :---: | :---: | :---: | :--- |
| OFF | OFF | OFF | OFF | OFF | Select Program No. 00 |
| OFF | OFF | OFF | OFF | ON | Select Program No. 01 |
| OFF | OFF | OFF | ON | OFF | Select Program No. 02 |
| OFF | OFF | OFF | ON | ON | Select Program No. 03 |
| OFF | OFF | ON | OFF | OFF | Select Program No. 04 |
| OFF | OFF | ON | OFF | ON | Select Program No. 05 |
| OFF | OFF | ON | ON | OFF | Select Program No. 06 |
| OFF | OFF | ON | ON | ON | Select Program No. 07 |
| OFF | ON | OFF | OFF | OFF | Select Program No. 08 |
| OFF | ON | OFF | OFF | ON | Select Program No. 09 |
| OFF | ON | OFF | ON | OFF | Select Program No. 10 |
| OFF | ON | OFF | ON | ON | Select Program No. 11 |
| OFF | ON | ON | OFF | OFF | Select Program No. 12 |
| OFF | ON | ON | OFF | ON | Select Program No. 13 |
| OFF | ON | ON | ON | OFF | Select Program No. 14 |
| OFF | ON | ON | ON | ON | Select Program No. 15 |
| ON | OFF | OFF | OFF | OFF | Select Program No. 16 |
| ON | OFF | OFF | OFF | ON | Select Program No. 17 |
| ON | OFF | OFF | ON | OFF | Select Program No. 18 |
| ON | OFF | OFF | ON | ON | Select Program No. 19 |
| ON | OFF | ON | OFF | OFF | Select Program No. 20 |
| ON | OFF | ON | OFF | ON | Select Program No. 21 |
| ON | OFF | ON | ON | OFF | Select Program No. 22 |
| ON | OFF | ON | ON | ON | Select Program No. 23 |
| ON | ON | OFF | OFF | OFF | Select Program No. 24 |
| ON | ON | OFF | OFF | ON | Select Program No. 25 |
| ON | ON | OFF | ON | OFF | Select Program No. 26 |


| DI 08 | DI 09 | DI 10 | DI 11 | DI 12 | Pattern Selection |
| :---: | :---: | :---: | :---: | :---: | :--- |
| ON | ON | OFF | ON | ON | Select Program No. 27 |
| ON | ON | ON | OFF | OFF | Select Program No. 28 |
| ON | ON | ON | OFF | ON | Select Program No. 29 |
| ON | ON | ON | ON | OFF | Select Program No. 30 |
| ON | ON | ON | ON | ON | Select Program No. 31 |

## Model Interpretation

## Instruction

- Select the desired key number.

The arrow to the right marks the selection available.

- Make one desired selection each from Table I through III.
$A \operatorname{dot}(\bullet)$ denotes unrestricted availability.



## KEY NUMBER

| Description |  | Selection | Availability |  |
| :--- | :--- | :--- | :--- | :---: |
| Control Loop | Single Loop Control <br> Dual Loop Control | IPC5000S <br>  | $\downarrow$ | IPC5000D |

## TABLE I - I nput \& Outputs

| Input | Standard Input (2 Analog Inputs + 12 Digital Inputs) | $0 \_$ | $\bullet$ | $\bullet$ |
| :--- | :--- | :---: | :---: | :---: |
| Output | Standard Output (2 Analog Outputs + 12 Digital Outputs) | -0 | $\bullet$ | $\bullet$ |
|  | Standard Output + 2 Analog Outputs | -1 | $\bullet$ |  |

TABLE II - Options

| Communication | $\begin{aligned} & \text { RS-232C } \\ & \text { RS-232C, RS-485 (Modbus RTU) } \\ & \text { RS-232C, Ethernet (Modbus TCP) } \end{aligned}$ | $\begin{aligned} & 0_{1} \\ & 1_{1} \\ & 2_{1} \end{aligned}$ | - | - |
| :---: | :---: | :---: | :---: | :---: |
| Manual \& Cable | None <br> Manual CD <br> Manual CD, RS-232C Cable (connection with PC) | $\begin{array}{r} 0 \\ -1 \\ -1 \\ -2 \end{array}$ | - |  |

TABLE III - Language

| Display Language | English/Korean | 0 | - | - |
| :---: | :---: | :---: | :---: | :---: |

Honeywell
Extemal Dimension


Wring Diagram

## - Single Channel (IPC5000S)

Digital Input Digital Output Analog I/O Communication Supply


| No. | Terminal name | Function |
| :---: | :---: | :---: |
| 1 | DI_COM |  |
| 2 | DI1 | Digital input1 |
| 3 | DI2 | Digital input2 |
| 4 | DI3 | Digital input3 |
| 5 | DI4 | Digital input4 |
| 6 | D15 | Digital input5 |
| 7 | DI6 | Digital input6 |
| 8 | DI_COM |  |
| 9 | DI7 | Digital input7 |
| 10 | DI8 | Digital input8 |
| 11 | D19 | Digital input9 |
| 12 | DI10 | Digital input10 |
| 13 | DI11 | Digital input11 |
| 14 | DI12 | Digital input12 |
| $\begin{aligned} & 15 \\ & 16 \\ & 17 \\ & 18 \\ & 19 \\ & 20 \\ & \hline \end{aligned}$ | Not Connected |  |


| No. | Terminal name | Function |
| :---: | :--- | :--- |
| $\mathbf{1}$ | DO_COM1 |  |
| 2 | DO1 | Digital output1 |
| $\mathbf{3}$ | DO2 | Digital output2 |
| 4 | DO3 | Digital output3 |
| 5 | DO4 | Digital output4 |
| 6 | DO5 | Digital output5 |
| 7 | DO6 | Digital output6 |
| 8 | DO_COM2 |  |
| 9 | DO7 | Digital output7 |
| 10 | DO8 | Digital output8 |
| 11 | DO9 | Digital output9 |
| 12 | DO10 | Digital output10 |
| 13 | DO11 | Digital output11 |
| 14 | DO12 | Digital output12 |
| 15 | N.C. | Relay 1 |
| 16 | N.O. |  |
| 17 | COM | Relay 2 |
| 18 | N.C. |  |
| 19 | N.O. |  |
| 20 | COM |  |


| No. | Terminal name | Function |
| :---: | :--- | :--- |
| 1 | Output1(+) | $4 \sim 20 \mathrm{~mA}$, |
| 2 | Output1(-) | Voltage Pulse |
| 3 | Output2(+) | $4 \sim 20 \mathrm{~mA}$, |
| 4 | Output2(-) | Voltage Pulse |
| 5 |  |  |
| 6 | Not |  |
| 7 | Connected |  |
| 8 |  |  |
| 9 | Input1 (+) | RTD(A),mA,V,TC |
| 10 | Input1 (-) | RTD(b) |
| 11 | Input1(B) | RTD(B) |
| 12 |  |  |
| 13 |  |  |
| 14 |  |  |
| 15 |  |  |
| 16 | Not |  |
| 17 | Connected |  |
| 18 |  |  |
| 19 |  |  |
| 20 |  |  |



- Dual Channel Type (IPC5000D)



## Wananty / Remedy

Honeywell warrants goods of its manufacture as being free of defective materials and faulty workmanship. Contact your local sales office for warranty information. If warranted goods are returned to Honeywell during the period of coverage, Honeywell will repair or replace without charge those items it finds defective. The foregoing is Buyer's sole remedy and is in lieu of all other warranties, expressed or implied, including those of merchantability and fitness for a particular purpose. Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this printing. However, we assume no responsibility for its use. While we provide application assistance personally, through our literature and the Honeywell web site, it is up to the customer to determine the suitability of the product in the application.


[^0]:    * The analog input option has no functional assignment, available for future purpose only.

